

ON THE SHIFT-WINDOW PHENOMENON OF SUPER-FUNCTIONS

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ABSTRACT. Using exploded numbers we consider the exploded Descartes-plane $\overline{R^2} = \{(\overline{x}, \overline{y}) : x, y \in R\}$ in which have the graphs of super-functions. Of course certain parts of these graphs are visible in the traditional Descartes-plane R^2 , while the other parts may be invisible. To show the invisible parts we introduce the super shift - and screw transformations which result the shifted - and screwed Descartes - coordinate systems. For the sake of understanding the paper contains some examples, too.

1. COMPUTATION WITH EXPLODED NUMBERS

In [1] we introduced the exploded numbers with the operations of super-addition and super-multiplication

$$(1.1) \quad \overline{x} \text{---} \bigoplus \text{---} \overline{y} = \overline{x+y}, \quad x, y \in R,$$

and

$$(1.2) \quad \overline{x} \text{---} \bigodot \text{---} \overline{y} = \overline{x \cdot y}, \quad x, y \in R,$$

respectively. Moreover, the rules of super-subtraction and super-division

$$(1.3) \quad \overline{x} \text{---} \bigominus \text{---} \overline{y} = \overline{x-y}, \quad x, y \in R,$$

and

$$(1.4) \quad \overline{x} \text{---} \bigoslash \text{---} \overline{y} = \overline{x:y}, \quad x, y \in R, \quad y \neq 0,$$

were presented, too. The number $\overline{x}$ was called the exploded of the real number $x \in R$ and the set of exploded numbers is denoted by $\overline{R}$. Sometimes we say that $\overline{R}$ is the exploded real axis. For any real number $x \in (-1, 1)$ explosion means

$$(1.5) \quad \overline{x} = \text{area th } x.$$

Clearly, R is isomorphic with $\overline{R}$ by the transformation

$$\begin{aligned} x &\rightarrow \overline{x}, \\ + &\rightarrow \bigoplus, \\ \cdot &\rightarrow \bigodot. \end{aligned}$$

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Moreover,

$$(1.6) \quad 0 = \overline{0}$$

is the unit element of super-addition and the unit element of super-multiplication is $\overline{1}$.

Considering that by (1.5) for any $x \in (-1, 1)$ we have

$$(1.7) \quad \overline{-x} = -\overline{x}$$

for any $x \in \overline{R}$ its additive inverse is denoted by $(-x)$.

For any pair $x, y \in \overline{R}$ the arrangement

$$(1.8) \quad x < y \quad \text{if and only if} \quad \underline{x} < \underline{y}$$

was also introduced in [1] (see [1], Definition 1.7), where $\underline{x}$ is called the compressed of x , defined by the identity

$$(1.9) \quad \overline{(\underline{x})} = x, \quad x \in \overline{R}.$$

Clearly, for any $x \in \overline{R}$ we have $\underline{x} \in R$. The inverse of explosion is called compression. Moreover,

$$(1.10) \quad \underline{x} = \text{th } x \quad \text{if} \quad -\infty < x < \infty,$$

and we also use the identity

$$(1.11) \quad \overline{(\underline{x})} = x, \quad x \in R.$$

Clearly, for any $x \in R$ and $x \in \overline{R}$

$$(1.12) \quad \overline{-x} = -\overline{x} \quad \text{and} \quad \underline{-x} = -\underline{x},$$

respectively. If $x \in \overline{R}$ and $x \leq -\overline{1}$ or $x \geq \overline{1}$ we say that x is invisible. The visible subset of the exploded real axis $\overline{R}$ is the real axis R itself. So, if $x \in R$ then $-\overline{1} < x < \overline{1}$.

2. SUPER-FUNCTIONS AND SUPER-CURVES

The concept of super-function was introduced in [1]. (See [1], (part 4).) Considering a basic function f with its definition-domain belonging to R we said that an $x \in \overline{R}$ belongs to the definition-domain of super-function $\text{spr } f$ if $f(\underline{x})$ is defined. Moreover,

$$(2.1) \quad \text{spr } f(x) = \overline{f(\underline{x})}.$$

Remark 2.2. If $S \subset \overline{R}$ and for any $x \in S$

$$(2.3) \quad y = F(x)$$

is unambiguous, then F is a super-function.

Really, considering

$$f_F(x) = \underline{F(\underline{x})}, \quad x \in \underline{S} \subset R$$

where $\underline{S}$ is the set of the compressed numbers of elements belonging to S as a basic function, we have by (2.1) and (1.9) that

$$\text{spr } f_F(x) = \overline{f_F(\underline{x})} = \overline{(F(\underline{(\underline{x})}))} = F(x).$$

The graphs of super-functions are situated in the exploded Descartes-plane $\overline{R^2}$ which is a super-linear space with the operations

$$X \oplus Y = (x_1 \oplus y_1, x_2 \oplus y_2), \quad X = (x_1, x_2), \quad Y = (y_1, y_2)$$

and

$$c \text{---}\bigcirc \text{---} X = (c \text{---}\bigcirc \text{---} x_1, c \text{---}\bigcirc \text{---} x_2), \quad x_1, x_2, y_1, y_2 \text{ and } c \in \overline{R}$$

as well as

$$X \text{---}\bigcirc \text{---} Y = (x_1 \text{---}\bigcirc \text{---} y_1, x_2 \text{---}\bigcirc \text{---} y_2).$$

Moreover, $\overline{R^2}$ is a super-euclidian space with the super-inner-product

$$X \text{---}\bigcirc \text{---} Y = (x_1 \text{---}\bigcirc \text{---} y_1) \text{---}\bigoplus \text{---} (x_2 \text{---}\bigcirc \text{---} y_2)$$

and it is super-normed with

$$\|X\|_{\overline{R^2}} = \text{spr} \sqrt{X \text{---}\bigcirc \text{---} X}.$$

If $X, Y, Z \in \overline{R^2}$ and $X \neq Z, Y \neq Z$ then we say

$$(2.4) \quad \text{meas} \text{---}\text{spr} \angle XZY = \text{spr} \arccos \left(((X \text{---}\bigcirc \text{---} Z) \text{---}\bigcirc \text{---} (Y \text{---}\bigcirc \text{---} Z)) \text{---}\bigcirc \text{---} \right. \\ \left. (\|X \text{---}\bigcirc \text{---} Z\|_{\overline{R^2}} \text{---}\bigcirc \text{---} \|Y \text{---}\bigcirc \text{---} Z\|_{\overline{R^2}}) \right).$$

The super-curve G is defined as follows:

$$G = \{X = (x, y) \in \overline{R^2} : x = x(t), y = y(t), \quad \alpha \leq t \leq \beta, \quad (\alpha, \beta) \subset \overline{R}\}$$

such that $u = \underline{x(t)}$ and $v = \underline{y(t)}$ are continuously differentiable functions of the parameter $\varphi = \underline{t}$ on the interval $[\underline{\alpha}, \underline{\beta}]$. Moreover, we require for any $\varphi \in [\underline{\alpha}, \underline{\beta}]$ that

$$(u'(\varphi))^2 + (v'(\varphi))^2 \neq 0.$$

An important special case is the super-line $L_C(V)$ defined by the equation

$$(2.5) \quad X = C \text{---}\bigoplus \text{---} (t \text{---}\bigcirc \text{---} V), \quad t \in \overline{R},$$

where $C = (c_1, c_2), V = (v_1, v_2) \in \overline{R^2}$ are given such that

$$(2.6) \quad (v_1 \text{---}\bigcirc \text{---} v_1) \text{---}\bigoplus \text{---} (v_2 \text{---}\bigcirc \text{---} v_2) = \overline{1}.$$

The super measure of super-angle of super-lines $L_C(V)$ and $L_C(U)$ with

$$\|U\|_{\overline{R^2}} = \overline{1}$$

is defined as follows:

$$(2.7) \quad \text{meas} \text{---}\text{spr} \angle (L_C(V), L_C(U)) = \min(\text{spr} \arccos(V \text{---}\bigcirc \text{---} U), \\ \text{spr} \arccos(-V \text{---}\bigcirc \text{---} U)).$$

3. WINDOW PHENOMENON AND SHIFT-WINDOW PHENOMENON

Considering a super-curve G (which may be a graph of a super-function) the intersection

$$G \cap R^2$$

is called the window phenomenon of G (or a super-function of f). For example, the window phenomenon of the super-unit-circle with the centre origo $\|x\|_{\overline{R^2}} = \overline{1}$ is itself the super-unit-circle except for points $(-\overline{1}, 0), (0, \overline{1}), (\overline{1}, 0)$ and $(0, -\overline{1})$ which are invisible points in the window R^2 .

Considering a fixed point $(x_0, y_0) \in \overline{R^2}$ we introduce the super-shift transformation

$$(3.1) \quad \begin{aligned} x &= \xi \text{---} \bigoplus \text{---} x_0 \\ y &= \eta \text{---} \bigoplus \text{---} y_0 \end{aligned}$$

which moves the exploded Descartes-coordinate system “ x, y ” into the system “ ξ, η ” having the new coordinate axes “ ξ ” and “ η ” with the new origo (x_0, y_0) . While the Descartes-plane

$$\begin{aligned} -\overline{1} &< x < \overline{1} \\ -\overline{1} &< y < \overline{1} \end{aligned}$$

is moving on the exploded Descartes-plane $\overline{R^2}$ into the Descartes-plane

$$\begin{aligned} x_0 \text{---} \bigoplus \text{---} \overline{1} &< x < x_0 \text{---} \bigoplus \text{---} \overline{1} \\ y_0 \text{---} \bigoplus \text{---} \overline{1} &< y < y_0 \text{---} \bigoplus \text{---} \overline{1} \end{aligned}$$

we can see the another subset of $\overline{R^2}$. This transformation gives a new window on the wall $\overline{R^2}$.

We can observe this transformation on the compressed model where the compressed wall $\overline{R^2}$ is R^2 and the compressed window R^2 is $\underline{R^2}$, that is, the set of points $(\underline{x}, \underline{y})$ for which

$$\begin{aligned} -1 &< \underline{x} < 1 \\ -1 &< \underline{y} < 1 \quad (x, y) \in R^2. \end{aligned}$$

By the compression the super-shift transformation becomes the familiar shift-transformation

$$\begin{aligned} \underline{x} &= \underline{\xi} + \underline{x_0} \\ \underline{y} &= \underline{\eta} + \underline{y_0} \end{aligned}$$

and the new sub-window is the set of points $(\underline{x}, \underline{y})$ for which

$$\begin{aligned} \underline{x_0} - 1 &< \underline{x} < \underline{x_0} + 1 \\ \underline{y_0} - 1 &< \underline{y} < \underline{y_0} + 1. \end{aligned}$$

Example 3.2. In the window we can see the visible parts of graphs of super-parabola

$$y = x \text{---} \bigoplus \text{---} x, \quad x \in \overline{R}$$

and of super-square-root function $\text{spr } \sqrt{x} = \sqrt{\underline{x}}, x \geq 0$. Their super-curves have two common points $(0, 0)$ and $(\overline{1}, \overline{1})$ such that the latter is invisible. Using the super-shift transformation (3.1) with $(x_0, y_0) = (\overline{1}, \overline{1})$, the new equation of super-parabola is

$$\eta = (\xi \text{---} \bigoplus \text{---} \overline{2}) \text{---} \bigoplus \text{---} \xi, \quad \xi \in \overline{R}$$

while the super-square-root has the equation

$$\eta = \left(\sqrt{\xi \text{---} \bigoplus \text{---} \overline{1}} \right) \text{---} \bigoplus \text{---} \overline{1}, \quad -\overline{1} \leq \xi \in \overline{R}$$

having the equations of window-curves (window phenomenons)

$$\eta = \text{area th}((\text{th } \xi)(\text{th } \xi + 2)), \quad -\infty < \xi < \text{area th}(\sqrt{2} - 1)$$

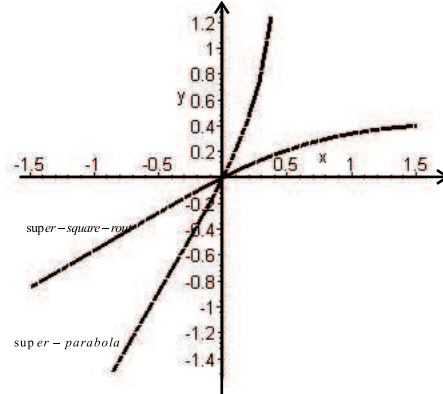


FIGURE 3.3.

and

$$\eta = \text{area th}(\sqrt{\text{th } \xi + 1} - 1), \quad -\infty < \xi < \infty,$$

respectively. Their intersection is visible in the new window:

Example 3.3. Considering the super-function

$$(3.4) \quad y = (\overline{2} - \odot - x) - \odot - (\overline{1} - \oplus - (x - \odot - x)), \quad x \in \overline{R}$$

by (1.6), (1.9), (1.2) (1.1), (1.4), (1.10) and (1.5) we can see that for any $x \in R$

$$\begin{aligned} (\overline{2} - \odot - x) - \odot - (\overline{1} - \oplus - (x - \odot - x)) &= \overline{\left(\frac{2x}{1 + (x)^2} \right)} = \\ &= \overline{\left(\frac{2 \text{th } x}{1 + \text{th}^2 x} \right)} = \overline{\text{th } 2x} = \text{area th}(\text{th } 2x) = 2x \end{aligned}$$

is obtained. This means that the (familiar) line, having the equation

$$(3.5) \quad y = 2x \quad (x \in R),$$

is the window-curve of the super-function defined under (3.4). In the window the graph of super-function appears to be a line. Applying the super-shift transformation (3.1) with $(x_0, y_0) = (\overline{1}, \overline{1})$ we have the new equation of the original super-function (3.4):

$$(3.6) \quad \eta = -((\xi - \odot - \xi) - \odot - (\overline{2} - \oplus - (\xi - \odot - (\xi - \oplus - \overline{2}))))), \quad \xi \in \overline{R}.$$

The window phenomenon of (3.6) has the equation

$$(3.7) \quad \eta = \frac{1}{2} \ln \frac{2(e^{4\xi} + e^{2\xi})}{3e^{4\xi} + 1}, \quad \xi \in R$$

and we can see it in the shift-window which is the following subset of $\overline{R}$:

$$(3.8) \quad \begin{aligned} 0 &< x < \overline{2} \\ 0 &< y < \overline{2}. \end{aligned}$$

Let us consider the points $O = (0, 0)$, $P_1 = (\frac{1}{2}, 1)$, $P_2 = (1, 2)$ and $\Omega = (\overline{1}, \overline{1})$ of the graph of super-function (3.4). Points O , P_1 , and P_2 are situated on the line

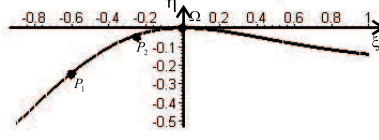


FIGURE 3.9.

(3.5) but Ω is invisible. On the other hand P_1 , P_2 and Ω has new coordinates in the Descartes-system “ ξ, η ”:

$$\left(\frac{1}{2}, 1\right), \left(1, 2\right) \quad \text{and} \quad (0, 0)$$

respectively, so we can see them in the shift-window (3.8) on the window-phenomenon (3.7):

In Fig. 3.9 the point O is invisible. However, another super-shift transformation, namely (3.1) with

$$(x_0, y_0) = \left(\frac{1}{2}, \frac{1}{2}\right),$$

results that O, P_1, P_2 and Ω are visible in the new window. In this case, the new equation of the super-function defined under (3.4) is

$$(3.10) \quad \eta = \left(\left(\left(-\frac{1}{2} \right) - \xi \right) - \left(\left(\frac{3}{2} \right) - \xi \right) - \left(\left(\frac{3}{8} \right) - \xi \right) - \left(\left(\frac{5}{4} \right) - \xi \right) \right) - \left(\left(\left(-\frac{1}{2} \right) - \xi \right) - \left(\left(\frac{3}{2} \right) - \xi \right) - \left(\left(\frac{3}{8} \right) - \xi \right) - \left(\left(\frac{5}{4} \right) - \xi \right) \right), \quad \xi \in \mathbb{R}$$

The window phenomenon of (3.10) has the equation

$$(3.11) \quad \eta = \text{area th} \frac{-\frac{1}{2}(\text{th } \xi)^2 + \frac{3}{2} \text{th } \xi + \frac{3}{8}}{(\text{th } \xi)^2 + \text{th } \xi + \frac{5}{4}}, \quad \text{area th}(\sqrt{3} - \frac{5}{2}) < \xi < \infty$$

and we have:

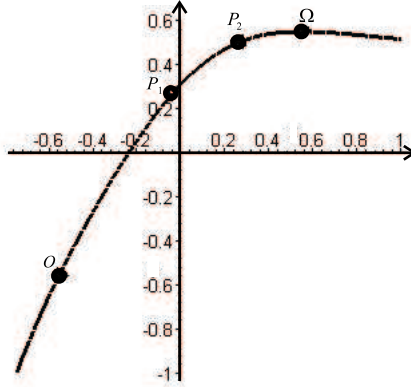


FIGURE 3.12.

The case of super-shift transformation (3.1) with $(x_0, y_0) = (0, \overline{1})$:

$$x = \xi \quad \text{and} \quad y = \eta - \bigoplus - \overline{1}.$$

The new equation of super-function defined under (3.4) is the following:

$$(3.13) \quad \eta = - \left(((\overline{1} - \bigoplus - \xi) - \bigoplus - (\overline{1} - \bigoplus - \xi)) - \bigoplus - (\overline{1} - \bigoplus - (\xi - \bigoplus - \xi)) \right), \quad \xi \in \overline{R}$$

The window phenomenon of (3.13) is

$$(3.14) \quad \eta = \frac{1}{2} \ln \frac{e^{4\xi} - 1}{e^{4\xi} + 3}, \quad 0 < \xi < \infty,$$

which shows that both O and Ω are invisible:

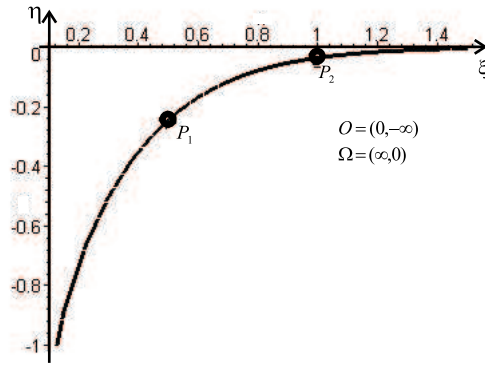


FIGURE 3.15.

The super-shift transformation (3.1) with $(x_0, y_0) = (\overline{1}, 0)$ is the most interesting. Now, the shift-window is the following subset of $\overline{R}^2$:

$$(3.16) \quad \begin{aligned} 0 < x < \overline{2} \\ -\infty < y < \infty. \end{aligned}$$

Similarly to the case mentined above, O and Ω are invisible again. The new equation of super-function defined under (3.4) is the following:

$$(3.17) \quad \eta = \left((\overline{2} - \bigoplus - \xi) - \bigoplus - \overline{2} \right) - \bigoplus - \left(((\xi - \bigoplus - \xi) - \bigoplus - (\overline{2} - \bigoplus - \xi)) - \bigoplus - \overline{2} \right), \quad \xi \in \overline{R}.$$

The window phenomenon of (3.17) has the equation

$$(3.18) \quad \eta = \text{area th} \frac{2(\text{th } \xi + 1)}{1 + (\text{th } \xi + 1)^2}, \quad -\infty < \xi < \infty, \quad \xi \neq 0$$

By Fig. 3.9, 3.12, 3.15 and 3.19 it seems that Ω is the maximum point of the graph of the super-function (3.4). Really, we have

Remark 3.20. Considering that for any $\underline{x} \in R$ the inequalities

$$-1 \leq \frac{2\underline{x}}{1 + (\underline{x})^2} \leq 1$$

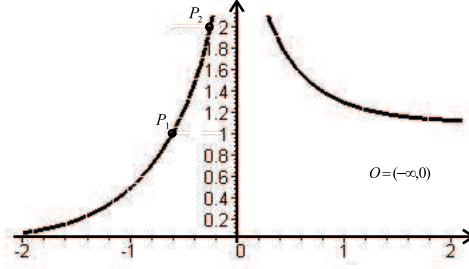


FIGURE 3.19.

are valid such that the equalities are valid if and only if the left-hand side, $\underline{x} = -1$ and, on the right-hand side, $\underline{x} = 1$. Hence (1.6), (1.7) and (1.8) yield

$$(3.21) \quad -\overline{1} \leq (\overline{2} \text{---} \bigcirc \text{---} x) \text{---} \bigcirc \text{---} (\infty \text{---} \bigoplus \text{---} (x \text{---} \bigcirc \text{---} x)) \leq \overline{1}, \quad x \in \overline{\mathcal{R}}$$

with the equalities on the left-hand or right-hand sides in the cases $x = -\overline{1}$ or $x = \overline{1}$, respectively.

Remark 3.22. By (3.21) we can see that the super-function defined under (3.4) is bounded but not constant. So, we have that (3.4) is not a super-line though its window phenomenon is line (3.5).

Example 3.23. Let us consider the super-square determined by the super-lines

$$(3.23) \quad \begin{aligned} L_{1,0} &: y = x \\ L_{-\infty,\infty} &: y = \overline{1} \text{---} \bigcirc \text{---} x \\ L_{\infty,-\infty} &: y = x \text{---} \bigcirc \text{---} \overline{1} \\ L_{-\infty,0} &: y = -x \end{aligned}$$

Using the super-shift transformation (3.1) with $(x_0, y_0) = ((\frac{\overline{1}}{2}), 0)$ we can see the symmetric form of the super-square in the shift window:

$$\begin{aligned} (\frac{\overline{1}}{2}) &< x < (\frac{\overline{3}}{2}) \\ -\infty &< y < \infty \end{aligned}$$

where the new equations of super-lines are:

$$\begin{aligned} L_{\infty,0} &: \eta = \xi \text{---} \bigoplus \text{---} (\frac{\overline{1}}{2}) \\ L_{-\infty,\infty} &: \eta = (\frac{\overline{1}}{2}) \text{---} \bigcirc \text{---} \xi \\ L_{\infty,-\infty} &: \eta = \xi \text{---} \bigcirc \text{---} (\frac{\overline{1}}{2}) \\ L_{-\infty,0} &: \eta = -(\xi \text{---} \bigoplus \text{---} (\frac{\overline{1}}{2})) \end{aligned}$$

with the equations of window phenomena $y = \text{area th}(\text{th } \xi + \frac{1}{2})$, $y = \text{area th}(\frac{1}{2} - \text{th } \xi)$, $y = \text{area th}(\text{th } \xi - \frac{1}{2})$, and $y = -\text{area th}(\text{th } \xi + \frac{1}{2})$, respectively.

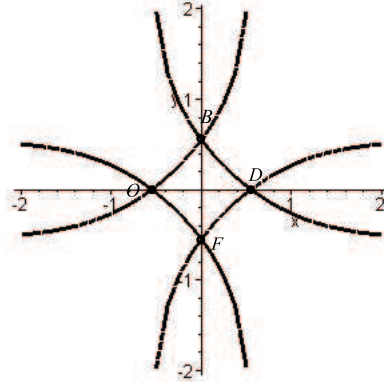


FIGURE 3.24.

Example 3.25. That the super-lines

$$L_{\infty, \infty} : y = x \text{ --- } \odot \text{ --- } \overline{1}$$

$$L_{2,0}^{\perp} : y = \overline{2} \text{ --- } \odot \text{ --- } x$$

have the common (invisible) point $M = (\overline{1}, \overline{2})$. It is easy too see that point $Q = (-\overline{1}, 0)$ lies on $L_{\infty, \infty}$ and $O = (0, 0)$ lies on $L_{2,0}^{\perp}$. Using (2.4), by (1.1) - (1.4), (1.6), (1.7) and (2.1) we compute

$$\text{meas spr} \angle QMO = \text{area th}(\arccos \frac{3}{\sqrt{10}}).$$

By the super-shift transformation (3.1) with $(x_0, y_0) = M$, we can see the intersection in the shift-window:

$$\begin{aligned} 0 &< x < \overline{2} \\ \overline{1} &< y < \overline{3}. \end{aligned}$$

Now, the new equations of super-lines are

$$L_{\infty, \infty} : \eta = \xi$$

$$L_{2,0}^{\perp} : \eta = \overline{2} \text{ --- } \odot \text{ --- } \xi$$

with the equations of shift-window phenomena $\eta = \xi$, $(\xi \in R)$ and $\eta = \text{area th}(2 \text{ th } \xi)$, $(|\xi| < \text{area th } \frac{1}{2})$ respectively.

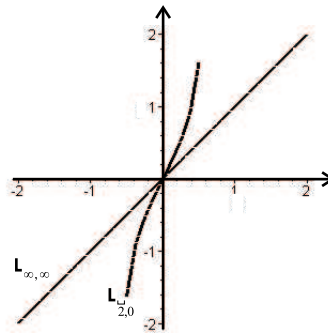


FIGURE 3.26.

Example 3.27. Let us consider super-lines

$$(3.28) \quad L_C(V) : X = C \text{---}\bigoplus\text{---}(t \text{---}\bigoplus\text{---} V)$$

and

$$(3.29) \quad L_C(U) : X = C \text{---}\bigoplus\text{---}(t \text{---}\bigoplus\text{---} U),$$

where

$$C = \left(\overline{\left(\frac{2+\sqrt{3}}{2}\right)}, \overline{\left(\frac{\sqrt{3}}{2}\right)} \right), \quad V = \left(\overline{\sqrt{\frac{2+\sqrt{3}}{4}}}, \overline{\sqrt{\frac{2-\sqrt{3}}{4}}} \right)$$

and

$$U = \left(\overline{\sqrt{\frac{1}{2}}}, \overline{\sqrt{\frac{1}{2}}} \right).$$

Computing their super-angle by (1.1), (1.2), (1.8), (1.9), (1.12), (2.1) and (2.7)

$$\text{meas spr } \angle(L_C(V), L_C(U)) = \overline{\left(\frac{\pi}{6}\right)}$$

is obtained, but the intersection of super-lines cannot be seen in the window.

Now, using the super-shift transformation (3.1) with $(x_0, y_0) = C$, we can see it in the shift-window:

$$\begin{aligned} \overline{\left(\frac{\sqrt{3}}{2}\right)} &< x < \overline{\left(2 + \frac{\sqrt{3}}{2}\right)} \\ \overline{\left(\frac{\sqrt{3}}{2} - 1\right)} &< y < \overline{\left(1 + \frac{\sqrt{3}}{2}\right)}. \end{aligned}$$

Considering that the equations under (3.28) and (3.29) are equivalent with the equations:

$$y = \overline{\left(\frac{\sqrt{3}}{2}\right)} \text{---}\bigoplus\text{---}(2 - \sqrt{3} \text{---}\bigoplus\text{---}(x \text{---}\bigoplus\text{---}\overline{\left(\frac{2+\sqrt{3}}{2}\right)}))$$

and

$$y = x \text{---}\bigoplus\text{---}\overline{1},$$

respectively. Hence, the new equations of super-lines

$$L_C(V) : \eta = \overline{2 - \sqrt{3}} \text{---}\bigoplus\text{---}\xi, \quad \xi \in \overline{R}$$

and

$$L_C(U) : \eta = \xi, \quad \xi \in \overline{R}.$$

Moreover, their shift-window phenomena have equations

$$\eta = \text{area th}((2 - \sqrt{3}) \text{th } \xi), \quad \xi \in R$$

and

$$\eta = \xi, \quad \xi \in R,$$

respectively, and have the graphs below:

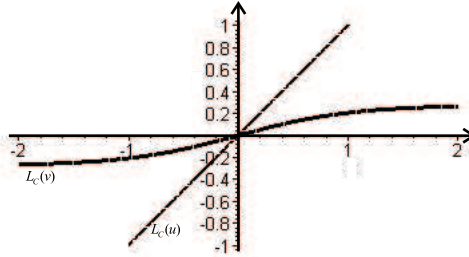


FIGURE 3.30.

4. SCREW TRANSFORMATION

Having the exploded Descartes-coordinate system “ x, y ”, for any point $(x, y) \in \overline{R^2}$ we introduce the screw coordinates ω and ϑ by the equation system

$$(4.1) \quad \begin{aligned} x &= (\omega \text{---}\odot\text{---} \text{spr} \cos \varphi_0) \text{---}\oplus\text{---} (\vartheta \text{---}\odot\text{---} \text{spr} \sin \varphi_0) \\ y &= (\omega \text{---}\odot\text{---} \text{spr} \sin \varphi_0) \text{---}\oplus\text{---} (\vartheta \text{---}\odot\text{---} \text{spr} \cos \varphi_0) \end{aligned}$$

where $\varphi_0 \in \overline{R}$ is a given (exploded) number. The transformation given by the equation system (4.1) is called screw transformation. The name of coordinate system “ ω, ϑ ” is the screwed system.

By (1.1), (1.2), (1.6), (1.9) and (2.1) for any $\varphi \in \overline{R}$ we easily prove the identity

$$(\text{spr} \sin \varphi \text{---}\odot\text{---} \text{spr} \sin \varphi) \text{---}\oplus\text{---} (\text{spr} \cos \varphi \text{---}\odot\text{---} \text{spr} \cos \varphi) = \overline{1}$$

and using it, we can solve the equation system (4.1) for ω and ϑ , so

$$(4.2) \quad \begin{aligned} \omega &= (x \text{---}\odot\text{---} \text{spr} \cos \varphi_0) \text{---}\oplus\text{---} (y \text{---}\odot\text{---} \text{spr} \sin \varphi_0) \\ \vartheta &= (y \text{---}\odot\text{---} \text{spr} \cos \varphi_0) \text{---}\oplus\text{---} (x \text{---}\odot\text{---} \text{spr} \sin \varphi_0). \end{aligned}$$

The equation systems (4.1) and (4.2) show the mutual and unambiguous connection between coordinates (x, y) and (ω, ϑ) which characterise the same point of $\overline{R^2}$. The systems “ x, y ” and “ ω, ϑ ” have a common origo.

Considering the points characterised by

$$(4.3) \quad \vartheta = 0$$

the equation system (4.1) yields

$$(4.4) \quad \begin{aligned} x &= \omega \text{---}\odot\text{---} \text{spr} \cos \varphi_0 \\ y &= \omega \text{---}\odot\text{---} \text{spr} \sin \varphi_0. \end{aligned}$$

If

$$\varphi_0 = \overline{k} \text{---}\odot\text{---} \overline{2\pi}, \quad k = 0, \pm 1, \pm 2, \dots$$

then by (4.4)

$$\vartheta = 0 \quad \text{if and only if} \quad y = 0,$$

and the screw transformation is identical.

If

$$\varphi_0 = \overline{\pi} - \bigoplus - (\overline{k} - \bigoplus - \overline{2\pi}), \quad k = 0, \pm 1, \pm 2, \dots$$

then by (4.4)

$$\vartheta = 0 \quad \text{if and only if} \quad y = 0,$$

but the point $(x, y) = (\overline{1}, 0)$ has the new coordinates $(\omega, \vartheta) = (-\overline{1}, 0)$.

If

$$\varphi_0 = \overline{\left(\frac{\pi}{2}\right)} - \bigoplus - (\overline{k} - \bigoplus - \overline{2\pi}), \quad k = 0, \pm 1, \pm 2, \dots$$

then

$$(4.5) \quad \vartheta = 0 \quad \text{if and only if} \quad x = 0,$$

and the point $(x, y) = (\overline{1}, 0)$ has the new coordinates $(\omega, \vartheta) = (0, \overline{1})$.

If

$$\vartheta_0 = \overline{\left(-\frac{\pi}{2}\right)} - \bigoplus - (\overline{k} - \bigoplus - \overline{2\pi}), \quad k = 0, \pm 1, \pm 2, \dots$$

then

$$(4.6) \quad \vartheta = 0 \quad \text{if and only if} \quad x = 0,$$

but the point $(x, y) = (\overline{1}, 0)$ has the new coordinates $(\omega, \vartheta) = (0, -\overline{1})$.

In general, except for the cases (4.5) and (4.6), the equation system (4.4) yields

$$(4.7) \quad \vartheta = 0 \quad \text{if and only if} \quad y = (\text{spr tg } \varphi_0) - \bigoplus - x,$$

that is, the “ ω -axis” of the screwed system is a super-line in the exploded Descartes-coordinate system “ x, y ”.

Similarly, considering the points characterised by

$$(4.8) \quad \omega = 0,$$

the equation system (4.1) yields

$$(4.9) \quad \begin{aligned} x &= -(\vartheta - \bigoplus - \text{spr sin } \varphi_0) \\ y &= \vartheta - \bigoplus - \text{spr cos } \varphi_0. \end{aligned}$$

Hence, except for cases

$$\varphi_0 = \overline{k} - \bigoplus - \overline{\pi}, \quad k = 0, \pm 1, \pm 2, \dots$$

we have that

$$(4.10) \quad \omega = 0 \quad \text{if and only if} \quad y = (-\text{spr ctg } \varphi_0) - \bigoplus - x,$$

that is, the “ ϑ -axis” of the screwed system is a super-line in the exploded Descartes system “ x, y ”.

Moreover, for any $\varphi_0 \in \overline{R}$ we have

$$(4.11) \quad \text{meas spr} \triangleleft (\text{“}\omega\text{-axis”}, \text{“}\vartheta\text{-axis”}) = \overline{\left(\frac{\pi}{2}\right)}.$$

The window phenomena of screwed axes in the cases

$$\varphi_0 = \overline{k} - \bigoplus - \overline{\left(\frac{\pi}{4}\right)}, \quad k = 0, \pm 1, \pm 2, \dots$$

are lines.

In the special case $\varphi_0 = (\frac{\pi}{3})$, the window phenomena of screwed axes having the equations

$$\text{"}\omega\text{-axis"} : y = \text{area th}(\sqrt{3} \text{th } x), \quad |x| < \text{area th } \frac{1}{\sqrt{3}}$$

and

$$\text{"}\vartheta\text{-axis"} : y = -\text{area th}\left(\frac{\text{th } x}{\sqrt{3}}\right), \quad x \in R$$

are situated in the following figure:

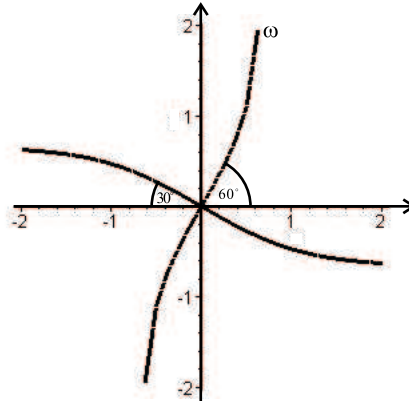


FIGURE 4.12.

5. CRITERION FOR SUPER-LINES

Now turning to the lines with equations

$$(5.1) \quad y = -x, \quad x \in R$$

and

$$(5.2) \quad y = 1 - x, \quad x \in R$$

we can consider as the window phenomena of some kind of super-functions. Clearly, the equation

$$(5.3) \quad y = -x, \quad x \in \overline{R}$$

represents a super-line and its window phenomenon has the equation under (5.1). The case of (5.2) is more complicated. Using (1.1) - (1.4) we can write for any $x \in R$

$$1 - x = (1 \text{---} \bigcirc \text{---} x) \text{---} \bigcirc \text{---} (\overline{1} \text{---} \bigcirc \text{---} (1 \text{---} \bigcirc \text{---} x))$$

which means that the super-function represented by the equation

$$(5.4) \quad y = (1 \text{---} \bigcirc \text{---} x) \text{---} \bigcirc \text{---} (\overline{1} \text{---} \bigcirc \text{---} (1 \text{---} \bigcirc \text{---} x)), \quad x \in \overline{R}, \quad x \neq \overline{\left(\frac{1}{1}\right)} (> \infty),$$

has the window phenomenon with equation (5.2). The graph of this super-function is not a super-line because starting from

$$(5.5) \quad f(x) = \frac{\text{th } 1 - x}{1 - (\text{th } 1)x}, \quad x \in R, \quad x \neq \frac{1}{\text{th } 1}$$

by (1.2)-(1.4), (1.6), (1.10) and (2.1) we have

$$\text{spr } f(x) = (1 \text{---} \bigcirc \text{---} x) \text{---} \bigcirc \text{---} (\overline{1} \text{---} \bigcirc \text{---} (1 \text{---} \bigcirc \text{---} x)), \quad x \neq \frac{1}{\text{th } 1}.$$

Having that (5.5) gives a hyperbola we can say that the super-function (5.4) represents a super-hyperbola.

To see this super-hyperbola in a better position, we use the super-shift transformation (3.1) with

$$(x_0, y_0) = \left(\overline{\left(\frac{1}{\text{th } 1} \right)}, \overline{\left(\frac{1}{\text{th } 1} \right)} \right).$$

Now the equation (instead of (5.4)) of super-hyperbola is:

$$(5.6) \quad \eta = \overline{\left(\frac{1}{\text{th } 1} \right)^2 - 1} - \odot - \xi, \quad \xi \in \overline{R}, \quad \xi \neq 0$$

and we can see its window phenomenon

$$\eta = \text{area th } \frac{\left(\frac{1}{\text{th } 1} \right)^2 - 1}{\text{th } \xi}, \quad |\xi| > \text{area th} \left(\left(\frac{1}{\text{th } 1} \right)^2 - 1 \right)$$

in the shift-window:

$$\begin{aligned} \text{area th} \left(\frac{1}{\text{th } 1} - 1 \right) < x < \overline{1 + \frac{1}{\text{th } 1}} \\ \text{area th} \left(\frac{1}{\text{th } 1} - 1 \right) < y < \overline{1 + \frac{1}{\text{th } 1}}, \end{aligned}$$

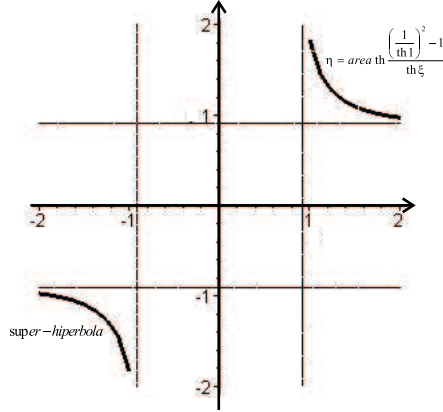


FIGURE 5.7.

Considering the sets

$$S_{x_0} = \{(x, y) \in \overline{R^2} : x = x_0, \quad y \in \overline{R} \text{ is arbitrary}\}$$

and

$$S_{y_0} = \{(x, y) \in \overline{R^2} : x \in \overline{R} \text{ is arbitrary, } y = y_0\}.$$

We see at a glance, that their points form super-lines. (The cases $x_0 = 0$ and $y_0 = 0$ are the exploded coordinate-axes.)

If x is running over $\overline{R}$, and $y = F(x)$ represents a mutual and unambiguous connection between x and $y \in \overline{R}$, it is not trivial whether the set

$$(5.8) \quad S = \{(x, y) \in \overline{R^2} : x \in \overline{R} \text{ is arbitrary and } y = F(x)\}$$

forms a super-line or not. (Exceptions are $F(x) = x$ and $F(x) = -x$.) Now we give a criterion in

Theorem 5.9. *Let us assume that x is running over $\overleftarrow{R}$ and $y = F(x)$ is a mutual and unambiguous connection between x and $y \in \overleftarrow{R}$. The set (5.8) forms a super-line if and only if there exists one and only one $x_0 \in \overleftarrow{R}$ so that*

$$(5.10) \quad F(x_0) = 0,$$

moreover, there exists a $\varphi_0 \in \overleftarrow{R}$, $\varphi_0 \neq \overleftarrow{k} \text{---} \overleftarrow{\bigcirc} \text{---} \overleftarrow{(\frac{\pi}{2})}$, $k = 0, \pm 1, \dots$ such that the transformations first, the super-shift transformation

$$(5.11) \quad \begin{aligned} x &= \xi \text{---} \overleftarrow{\bigoplus} \text{---} x_0 \\ y &= \eta \end{aligned}$$

second, the screw transformation

$$(5.12) \quad \begin{aligned} \xi &= (\omega \text{---} \overleftarrow{\bigcirc} \text{---} \text{spr} \cos \varphi_0) \text{---} \overleftarrow{\bigcirc} \text{---} (\vartheta \text{---} \overleftarrow{\bigcirc} \text{---} \text{spr} \sin \varphi_0) \\ \eta &= (\omega \text{---} \overleftarrow{\bigcirc} \text{---} \text{spr} \sin \varphi_0) \text{---} \overleftarrow{\bigoplus} \text{---} (\vartheta \text{---} \overleftarrow{\bigcirc} \text{---} \text{spr} \cos \varphi_0) \end{aligned}$$

result that the graph of super-function F becomes the “ ω -axis” of the coordinate-system “ ω, ϑ ” with the origo $(x_0, 0)$.

Example 5.13. Let us consider the set (5.8) with

$$F(x) = \overleftarrow{2} \text{---} \overleftarrow{\bigcirc} \text{---} x, \quad x \in \overleftarrow{R}.$$

In this case $x_0 = 0$ (see (5.10)), so the super-shift transformation is identical. (See (3.1) and (5.11).) Moreover, the screw transformation (5.12) with the necessary condition $\vartheta = 0$ has the form

$$x = \omega \text{---} \overleftarrow{\bigcirc} \text{---} \text{spr} \cos \varphi_0$$

$$\overleftarrow{2} \text{---} \overleftarrow{\bigcirc} \text{---} x = \omega \text{---} \overleftarrow{\bigcirc} \text{---} \text{spr} \sin \varphi_0.$$

Hence $\varphi_0 = \text{spr} \arctg \overleftarrow{2}$. So, the set (5.8) forms a super-line.

Example 5.14. Let us consider the set (5.8) with

$$F(x) = \text{spr} \arctg x, \quad x \in \overleftarrow{R}. \quad (\text{See (2.1).})$$

In this case $x_0 = 0$ (see (5.10)), so the super-shift transformation is identical. (See (3.1) and (5.11).) Moreover, the screw transformation (5.12) with the necessary condition $\vartheta = 0$ yields

$$x = \omega \text{---} \overleftarrow{\bigcirc} \text{---} \text{spr} \cos \varphi_0$$

$$\text{spr} \arctg x = \omega \text{---} \overleftarrow{\bigcirc} \text{---} \text{spr} \sin \varphi_0$$

Hence,

$$\begin{aligned} \text{spr} \arctg \varphi_0 &= (\text{spr} \arctg x) \text{---} \overleftarrow{\bigcirc} \text{---} x = \\ &= \overleftarrow{\arctg x} \text{---} \overleftarrow{\bigcirc} \text{---} \overleftarrow{(x)} = \overleftarrow{\left(\frac{\arctg x}{x} \right)} \end{aligned}$$

depends on x , so φ_0 does not exist.

6. PROOF OF THEOREM 5.9.

We need the following

Lemma 6.1. *If $v_1 \in \overline{R^+}$, v_1 and v_2 satisfy condition (2.6) then we have*

$$(6.2) \quad \text{spr sin}(\text{spr arc tg}(v_2 \text{---}\odot\text{---}v_1)) = v_2$$

and

$$(6.3) \quad \text{spr cos}(\text{spr arc tg}(v_2 \text{---}\odot\text{---}v_1)) = v_1.$$

Proof of the Lemma. Using (2.1), (1.9), (1.4) and (1.11) we get

$$\begin{aligned} \text{spr arc tg}(v_2 \text{---}\odot\text{---}v_1) &= \overline{\text{arc tg } v_2 \text{---}\odot\text{---}v_1} = \\ &= \overline{\text{arc tg } \underline{v_2} \text{---}\odot\text{---}\underline{v_1}} = \overline{\text{arc tg } \underline{v_2 : v_1}} = \\ &= \overline{\text{arc tg}(\underline{v_2 : v_1})}. \end{aligned}$$

Moreover, (2.6) implies

$$(\underline{v_1})^2 + (\underline{v_2})^2 = 1.$$

Hence, using that $\underline{v_1} > 0$ (see (1.8)) we get

$$\sin\left(\text{arc tg } \frac{\underline{v_2}}{\underline{v_1}}\right) = \underline{v_2}.$$

Moreover, (2.1), (1.11) and (1.9) yield

$$\begin{aligned} \text{spr sin}(\text{spr arc tg}(v_2 \text{---}\odot\text{---}v_1)) &= \overline{\sin \text{spr arc tg}(v_2 \text{---}\odot\text{---}v_1)} \\ &= \overline{\sin(\text{arc tg}(\underline{v_2 : v_1}))} = \overline{(\underline{v_2})} = v_2, \end{aligned}$$

that is we have (6.2).

Similarly,

$$\cos(\text{arc tg } \frac{\underline{v_2}}{\underline{v_1}}) = \underline{v_1}$$

implies

$$\text{spr cos}(\text{spr arc tg}(v_2 \text{---}\odot\text{---}v_1)) = v_1$$

that is we have (6.3). □

Proof of Theorem. Necessity. Let us assume that set S (see (5.8)) forms a super-line which has the equation system

$$\begin{aligned} x &= c_1 \text{---}\oplus\text{---}(t \text{---}\odot\text{---}v_1) \\ y &= c_2 \text{---}\oplus\text{---}(t \text{---}\odot\text{---}v_2) \end{aligned}$$

where $C = (c_1, c_2)$ and $V = (v_1, v_2)$ with (2.6) belong to $\overline{R^2}$. As the connection between x and y is mutual and unambiguous, v_1 and v_2 are different from 0. Moreover, we can assume that $v_1 > 0$. Hence, we have that

$$(6.4) \quad y = (m \text{---}\odot\text{---}x) \text{---}\oplus\text{---}b$$

where

$$(6.5) \quad m = v_2 \text{---}\odot\text{---}v_1, (m \neq 0)$$

and

$$b = c_2 \text{---} \bigcirc \text{---} (m \text{---} \bigcirc \text{---} c_1),$$

that is

$$(6.6) \quad F(x) = (m \text{---} \bigcirc \text{---} x) \text{---} \bigoplus \text{---} b$$

is a super-linear function. Now, by (6.6) we have

$$(6.7) \quad x_{\left(\begin{smallmatrix} 0 \\ 0 \end{smallmatrix}\right)} = (-b) \text{---} \bigcirc \text{---} m$$

as the unique point such that

$$F(x_{\left(\begin{smallmatrix} 0 \\ 0 \end{smallmatrix}\right)}) = 0,$$

so (5.10) is fulfilled. Let now

$$(6.8) \quad \varphi_0 = \text{spr arc tg } m.$$

Clearly, $\varphi_0 \neq \overline{k} \text{---} \bigcirc \text{---} (\frac{\pi}{2})$, $k = 0, \pm 1, \pm 2, \dots$ Using transformation (5.11) with $x_0 = x_{\left(\begin{smallmatrix} 0 \\ 0 \end{smallmatrix}\right)}$, by (6.4) and (6.7) we have the equation super-line (5.8) with (6.6) in the system “ ξ, η ” with the origo $(x_{\left(\begin{smallmatrix} 0 \\ 0 \end{smallmatrix}\right)}, 0)$:

$$(6.9) \quad \eta = m \text{---} \bigcirc \text{---} \xi.$$

Considering transformation (5.12) with φ_0 under (6.8), by (6.5) and Lemma 6.1 we have

$$\begin{aligned} \xi &= (\omega \text{---} \bigcirc \text{---} v_1) \text{---} \bigcirc \text{---} (\vartheta \text{---} \bigcirc \text{---} v_2) \\ \eta &= (\omega \text{---} \bigcirc \text{---} v_2) \text{---} \bigoplus \text{---} (\vartheta \text{---} \bigcirc \text{---} v_1) \end{aligned}$$

Using (6.9) the equation

$$(6.10) \quad (\omega \text{---} \bigcirc \text{---} v_1) \text{---} \bigoplus \text{---} (\vartheta \text{---} \bigcirc \text{---} v_1) = m \text{---} \bigcirc \text{---} ((\omega \text{---} \bigcirc \text{---} v_1) \text{---} \bigcirc \text{---} (\vartheta \text{---} \bigcirc \text{---} v_2))$$

is the equation of super-line (5.8) in the coordinate system “ ω, ϑ ” with the origo $(x_{\left(\begin{smallmatrix} 0 \\ 0 \end{smallmatrix}\right)}, 0)$. Sperrmultiplying both sides of the equation (6.10) by v_1 and using (6.5) we can write

$$\begin{aligned} &((\omega \text{---} \bigcirc \text{---} v_2) \text{---} \bigcirc \text{---} v_1) \text{---} \bigoplus \text{---} ((\vartheta \text{---} \bigcirc \text{---} v_1) \text{---} \bigcirc \text{---} v_1) = \\ &= ((v_2 \text{---} \bigcirc \text{---} \omega) \text{---} \bigcirc \text{---} v_1) \text{---} \bigcirc \text{---} (v_2 \text{---} \bigcirc \text{---} (\vartheta \text{---} \bigcirc \text{---} v_2)). \end{aligned}$$

Hence

$$\vartheta \text{---} \bigcirc \text{---} ((v_1 \text{---} \bigcirc \text{---} v_1) \text{---} \bigoplus \text{---} (v_2 \text{---} \bigcirc \text{---} v_2)) = 0$$

and (2.6) gives that $\vartheta = 0$. This shows that super-line (5.8) lies on the “ ω -axis” of the coordinate-system “ ω, ϑ ”.

Sufficiency. Now we assume that there exists a (unique) x_0 with (5.10) and

$\varphi_0 \neq \overline{k} \text{---} \bigcirc \text{---} (\frac{\pi}{2})$ such that after the transformations (5.11) and (5.12) the points of the set S lie on the “ ω -axis” of the coordinate system “ ω, ϑ ” with the origo $(x_0, 0)$. These mean that if $(x, y) \in S$ having the coordinates ω and ϑ such that

$$\begin{aligned} x \text{---} \bigcirc \text{---} x_0 &= (\omega \text{---} \bigcirc \text{---} \text{spr cos } \varphi_0) \text{---} \bigcirc \text{---} (\vartheta \text{---} \bigcirc \text{---} \text{spr sin } \varphi_0) \\ y &= (\omega \text{---} \bigcirc \text{---} \text{spr sin } \varphi_0) \text{---} \bigoplus \text{---} (\vartheta \text{---} \bigcirc \text{---} \text{spr cos } \varphi_0) \end{aligned}$$

is valid with $\vartheta = 0$. Hence, for any $x \in \overline{R}$

$$x \text{---}\bigcirc \text{---} x_0 = \omega \text{---}\bigcirc \text{---} \text{spr} \cos \varphi_0$$

$$F(x) = \omega \text{---}\bigcirc \text{---} \text{spr} \sin \varphi_0$$

Having that $\text{spr} \cos \varphi_0 \neq 0$ and assuming that $x \neq x_0$ (that is $\omega \neq 0$) by (2.1) we can write

$$F(x) \text{---}\bigcirc \text{---} (x \text{---}\bigcirc \text{---} x_0) = \text{spr} \text{tg} \varphi_0 (\neq 0).$$

Moreover,

$$F(x) = (\text{spr} \text{tg} \varphi_0) \text{---}\bigcirc \text{---} (x \text{---}\bigcirc \text{---} x_0)$$

which, by (5.10), remains valid for $x = x_0$, too. As F is a super-linear function, the points of S form a super-line. $\square$

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