

DYNAMICS OF SPECIES IN A NONAUTONOMOUS LOTKA-VOLTERRA SYSTEM

TA VIET TON

ABSTRACT. In this paper, we study a Lotka-Volterra model with two predators and one prey.

The explorations involve the permanence, extinction, the existence, uniqueness and global asymptotic stability of a positive solution.

1. INTRODUCTION

In this paper, we consider the Lotka-Volterra model with Beddington-DeAngelis functional response of two predators and one prey.

$$(1) \quad \begin{cases} x' = x[a - bx] - \frac{cxy}{\alpha + \beta x + \gamma y} - mxz \\ y' = -dy + \frac{fxy}{\alpha + \beta x + \gamma y} - nyz \\ z' = -gz + \frac{h[my + nz]}{\xi + \eta z} \end{cases}$$

Here $x(t)$, $y(t)$ and $z(t)$ represent the population density of the two predator species, and of the prey at times t , respectively. $a(t)$, $b(t)$, $c(t)$, $d(t)$, $m(t)$, $f(t)$, $n(t)$, $g(t)$, $h(t)$, $\beta(t)$, $\gamma(t)$, $\eta(t)$ are continuous and bounded above and below by positive constants; $\alpha(t)$, $\xi(t)$ are continuous and nonnegative.

This paper is organized as follows. Section 2 provides some definitions and notations. In section 3 we state our main result of this paper for problem (1).

2. DEFINITION AND NOTATION

In this section we summarize the basic definitions and facts which are used later (cf. [7]). Let $\mathbb{R}_+^3 := \{(x, y, z) \in \mathbb{R}^3 | x \geq 0, y \geq 0, z \geq 0\}$. For a bounded

2000 *Mathematics Subject Classification.* 34D05.

Key words and phrases. Beddington-DeAngelis Predator-Prey system, permanence, extinction.

continuous function $g(t)$ on $\mathbb{R}$, we use the following notation:

$$g^u := \sup_{t \in \mathbb{R}} g(t), \quad g^l := \inf_{t \in \mathbb{R}} g(t).$$

Similarly to Lemma 1 in [10], one can easily prove that

Lemma 1. *Both the nonnegative and positive cones of $\mathbb{R}^3$ are positively invariant for (1).*

In the remainder of this paper, for biological reasons, we only consider the solutions $(x(t), y(t), z(t))$ with positive initial values, i.e., $x(t_0) > 0$, $y(t_0) > 0$ and $z(t_0) > 0$.

Definition 1. System (1) is said to be permanent if there exist positive constants δ, Δ with $0 < \delta < \Delta$ such that

$$\begin{aligned} \min\{\liminf_{t \rightarrow \infty} x(t), \liminf_{t \rightarrow \infty} y(t), \liminf_{t \rightarrow \infty} z(t)\} &\geq \delta, \\ \max\{\limsup_{t \rightarrow \infty} x(t), \limsup_{t \rightarrow \infty} y(t), \limsup_{t \rightarrow \infty} z(t)\} &\leq \Delta \end{aligned}$$

for all solutions of (1) with positive initial values. System (1) is said to be nonpersistent if there is a positive solution $(x(t), y(t), z(t))$ of (1) satisfying

$$\min\{\liminf_{t \rightarrow \infty} x(t), \liminf_{t \rightarrow \infty} y(t), \liminf_{t \rightarrow \infty} z(t)\} = 0.$$

Definition 2. A set A is called to be an ultimately bounded region of system (1) if for any solution $(x(t), y(t), z(t))$ of (1) with positive initial values, there exists $T_1 > 0$ such that $(x(t), y(t), z(t)) \in A$ for all $t \geq t_0 + T_1$.

Definition 3. A bounded nonnegative solution $(\hat{x}(t), \hat{y}(t), \hat{z}(t))$ of (1) is said to be globally asymptotically stable (or globally attractive) if any other solution $(x(t), y(t), z(t))$ of (1) with positive initial values satisfies

$$\lim_{t \rightarrow \infty} (|x(t) - \hat{x}(t)| + |y(t) - \hat{y}(t)| + |z(t) - \hat{z}(t)|) = 0.$$

Lemma 2. [2] *Let h be a real number and f be a nonnegative function defined on $[h, +\infty)$ such that f is integrable on $[h, +\infty)$ and is uniformly continuous on $[h, +\infty)$, then*

$$\lim_{t \rightarrow \infty} f(t) = 0.$$

3. MAIN RESULTS

Theorem 1. *If $m_1^\varepsilon > 0$, $m_2^\varepsilon > 0$ and $m_3^\varepsilon > 0$, then set Γ_ε defined by*

$$(2) \quad \Gamma_\varepsilon = \{(x, y, z) \in \mathbb{R}^3 \mid m_1^\varepsilon \leq x \leq M_1^\varepsilon, m_2^\varepsilon \leq y \leq M_2^\varepsilon, m_3^\varepsilon \leq z \leq M_3^\varepsilon\}$$

is positively invariant with respect to system (1), where

$$\begin{aligned} M_1^\varepsilon &:= \frac{a^u}{b^l} + \varepsilon, & m_1^\varepsilon &:= \frac{a^l \gamma^l - c^u}{b^u \gamma^l} - \frac{m^u M_3^\varepsilon}{b^u}, \\ M_2^\varepsilon &:= \frac{(f^u - d^l \beta^l) M_1^\varepsilon}{d^l \gamma^l}, & m_2^\varepsilon &:= \frac{f^l m_1^\varepsilon - (d^u + n^u M_3^\varepsilon)(\alpha^u + \beta^u m_1^\varepsilon)}{\gamma^u (d^u + n^u M_3^\varepsilon)}, \end{aligned}$$

$$M_3^\varepsilon := \frac{h^u(m^u M_1^\varepsilon + n^u M_2^\varepsilon) - g^l \xi^l}{g^l \eta^l}, \quad m_3^\varepsilon := \frac{h^l(m^u m_1^\varepsilon + n^u m_2^\varepsilon) - g^u \xi^u}{g^u \eta^u}$$

and $\varepsilon \geq 0$ is constant.

Proof. We know that the logistic equation

$$X'(t) = A(t)X(t)[B - X(t)] \quad (B \neq 0)$$

has a unique solution

$$X(t) = \frac{BX_0 e^{\int_{t_0}^t A(s)Bds}}{X_0[e^{\int_{t_0}^t A(s)Bds} - 1] + B}$$

where $X_0 := X(t_0)$. By Lemma 1, we have $x(t) > 0$, $y(t) > 0$ and $z(t) > 0$ for all $t \geq t_0$. Because $M_1^\varepsilon > x_0 > 0$ and (1), we have

$$x'(t) \leq x(t)[a(t) - b(t)x(t)] \leq x(t)[a^l - b^u x(t)] = b^u x(t)(M_1^0 - x).$$

Thus, by using a standard comparison argument, we obtain that

$$(3) \quad x(t) \leq \frac{x_0 M_1^0 e^{a^u(t-t_0)}}{x_0[e^{a^u(t-t_0)} - 1] + M_1^0} \leq \frac{x_0 M_1^\varepsilon e^{a^u(t-t_0)}}{x_0[e^{a^u(t-t_0)} - 1] + M_1^\varepsilon} < M_1^\varepsilon, \quad t \geq t_0.$$

Similarly, because

$$(4) \quad \begin{aligned} y' &\leq -d^l y + \frac{f^u x y}{\alpha^l + \beta^l x + \gamma^l y} \leq -d^l y + \frac{f^u M_1^\varepsilon y}{\alpha^l + \beta^l M_1^\varepsilon + \gamma^l y} \leq \\ &\leq \frac{[(f^u - d^l \beta^l) M_1^\varepsilon - d^l \gamma^l y] y}{\alpha^l + \beta^l M_1^\varepsilon + \gamma^l y} = \frac{d^l \gamma^l}{\alpha^l + \beta^l M_1^\varepsilon + \gamma^l y} y [M_2^\varepsilon - y], \quad t \geq t_0, \end{aligned}$$

and $0 < y_0 < M_2^\varepsilon$, we have

$$(5) \quad y(t) \leq M_2^\varepsilon \frac{y_0 e^{\int_{t_0}^t \frac{M_2^\varepsilon d^l \gamma^l}{\alpha^l + \beta^l M_1^\varepsilon + \gamma^l y(s)} ds}}{y_0 [e^{\int_{t_0}^t \frac{M_2^\varepsilon d^l \gamma^l}{\alpha^l + \beta^l M_1^\varepsilon + \gamma^l y(s)} ds} - 1] + M_2^\varepsilon} < M_2^\varepsilon, \quad t \geq t_0.$$

And because $0 < z_0 < M_3^\varepsilon$ and

$$\begin{aligned} z'(t) &\leq -g^l z + \frac{h^u z(m^u x + n^u y)}{\xi^l + \eta^l z} \\ &\leq -g^l z + \frac{h^u z(m^u M_1^\varepsilon + n^u M_2^\varepsilon)}{\xi^l + \eta^l z} \\ &= \frac{g^l \eta^l}{\xi^l + \eta^l z} z(M_3^\varepsilon - z), \end{aligned}$$

we also get that

$$(6) \quad z(t) < M_3^\varepsilon, \quad t \geq t_0.$$

Now, from (1), (3), (5) and (6), we have

$$\begin{aligned} x'(t) &\geq x \left(a^l - b^u x - \frac{c^u y}{\alpha^l + \gamma^l y} - m^u z \right) \\ &\geq x \left(a^l - b^u x - \frac{c^u M_2^\varepsilon}{\alpha^l + \gamma^l M_2^\varepsilon} - m^u M_3^\varepsilon \right) \\ &= b^u x (m_1^\varepsilon - x) \end{aligned}$$

and $x_0 > m_1^\varepsilon$. Thus,

$$x(t) \geq \frac{m_1^\varepsilon x_0 e^{b^u m_1^\varepsilon (t-t_0)}}{x_0 [e^{b^u m_1^\varepsilon (t-t_0)} - 1] + m_1^\varepsilon} > m_1^\varepsilon, \quad \text{for all } t \geq t_0.$$

Similarly, we have

$$\begin{aligned} y'(t) &\geq -d^u y + \frac{f^l m_1^\varepsilon}{\alpha^u + \beta^u m_1^\varepsilon + \gamma^u y} y - n^u M_3^\varepsilon y \\ &= \frac{\gamma^u (d^u + n^u M_3^\varepsilon)}{\alpha^u + \beta^u m_1^\varepsilon + \gamma^u y} y [m_2^\varepsilon - y], \end{aligned}$$

for which follows that $y(t) > m_2^\varepsilon$, for all $t \geq t_0$, and

$$\begin{aligned} z'(t) &\geq -g^u z + \frac{h^l z (m^u m_1^\varepsilon + n^u m_2^\varepsilon)}{\xi^u + \eta^u z} \\ &= \frac{g^u \eta^u}{\xi^u + \eta^u z} z (m_3^\varepsilon - z), \end{aligned}$$

for which follows that $z(t) > m_3^\varepsilon$, for all $t \geq t_0$. So the proof is complete. $\square$

Corollary 1. *If $m_1^\varepsilon > 0$, $m_2^\varepsilon > 0$ and $m_3^\varepsilon > 0$, then we have*

$$\begin{aligned} \liminf_{t \rightarrow \infty} x(t) &\geq m_1^\varepsilon, & \limsup_{t \rightarrow \infty} x(t) &\leq M_1^\varepsilon, \\ \liminf_{t \rightarrow \infty} y(t) &\geq m_2^\varepsilon, & \limsup_{t \rightarrow \infty} y(t) &\leq M_2^\varepsilon, \\ \liminf_{t \rightarrow \infty} z(t) &\geq m_3^\varepsilon, & \limsup_{t \rightarrow \infty} z(t) &\leq M_3^\varepsilon. \end{aligned}$$

Proof. From (3) we have $\limsup_{t \rightarrow \infty} x(t) < M_1^\varepsilon$. Thus there exists $t_1 \geq t_0$ such that

$$x(t) \leq M_1^\varepsilon, \quad t \geq t_1.$$

Similarly to (4) and (5) we obtain that

$$(7) \quad y(t) \leq M_2^\varepsilon \frac{y_1 e^{\int_{t_1}^t \frac{M_2^\varepsilon d^l \gamma^l}{\alpha^l + \beta^l M_1^\varepsilon + \gamma^l y(s)} ds}}{y_1 [e^{\int_{t_1}^t \frac{M_2^\varepsilon d^l \gamma^l}{\alpha^l + \beta^l M_1^\varepsilon + \gamma^l y(s)} ds} - 1] + M_2^\varepsilon}.$$

Thus, $0 < y(t) \leq \max\{M_2^\varepsilon, y_1\}$ for all $t \geq t_1$, where $y_1 := y(t_1)$. Therefore, from (7) we get that

$$\limsup_{t \rightarrow \infty} y(t) \leq M_2^\varepsilon.$$

As a consequence, there exists $t_2 \geq t_1$ such that $y(t) \leq M_3^\varepsilon$ for all $t \geq t_2$.

Similarly, we claim that

$$\begin{aligned} \limsup_{t \rightarrow \infty} z(t) &\leq M_3^\varepsilon, & \liminf_{t \rightarrow \infty} x(t) &\geq m_1^\varepsilon, \\ \liminf_{t \rightarrow \infty} y(t) &\geq m_2^\varepsilon, & \liminf_{t \rightarrow \infty} z(t) &\geq m_3^\varepsilon. \end{aligned}$$

The proof is complete. $\square$

Corollary 2. *If $m_1^\varepsilon > 0$, $m_2^\varepsilon > 0$ and $m_3^\varepsilon > 0$, then system (1) is permanent and set Γ_ε with $\varepsilon \geq 0$ defined by (2) is an ultimately bounded region of system (1).*

Using Corollary 1, it is easy to verify the statement of the above lemma.

Theorem 2. *If $M_2^0 < 0$ or $M_3^0 < 0$, then $\lim_{t \rightarrow \infty} y(t) = 0$ or $\lim_{t \rightarrow \infty} z(t) = 0$ respectively.*

Proof. We see that if $M_2^0 < 0$ or $M_3^0 < 0$ then $M_2^\varepsilon < 0$ or $M_3^\varepsilon < 0$, respectively, with ε is sufficiently small. Therefore, similarly to the proof of Theorem 1 we get that

$$(8) \quad y'(t) \leq \frac{d^l \gamma^l}{\alpha^l + \beta^l M_1^\varepsilon + \gamma^l y} y[M_2^\varepsilon - y]$$

and

$$z'(t) \leq \frac{g^l \eta^l}{\xi^l + \eta^l z} z[M_3^\varepsilon - z].$$

If $M_2^\varepsilon < 0$ then $y'(t) < 0$. Thus, $0 < y(t) \leq y(t_0)$, for all $t \geq t_0$ and then there exists $C_1 \geq 0$ such that

$$\lim_{t \rightarrow \infty} y(t) = C_1.$$

If $C_1 > 0$ then from system (1), (8) and $0 < C_1 \leq y(t) \leq y(t_0)$, $t \geq t_0$, we have that there exists $\mu > 0$ such that $y'(t) < -\mu$ for all $t \geq t_0$. Thus $y(t) < -\mu(t - t_0) + y_0$. Therefore, $\lim_{t \rightarrow \infty} y(t) = -\infty$. So we have a contraction to the fact that $y(t) > 0$ for all $t \geq t_0$. Hence,

$$\lim_{t \rightarrow \infty} y(t) = 0.$$

Similarly, if $M_3^\varepsilon < 0$ then $\lim_{t \rightarrow \infty} z(t) = 0$. The proof is complete. $\square$

Theorem 3. *Let $(x^*(t), y^*(t), z^*(t))$ be bounded positive solutions of system (1). If $m_1^\varepsilon > 0$, $m_2^\varepsilon > 0$ and $m_3^\varepsilon > 0$ and the following conditions hold:*

$$\inf_{t \geq t_0} \left\{ b(t) - \frac{\alpha(t)f(t)}{u(t, m_1^\varepsilon, m_2^\varepsilon)} - \frac{[\beta(t)c(t) + f(t)\gamma(t)]M_2^\varepsilon}{u(t, m_1^\varepsilon, m_2^\varepsilon)} - \frac{m(t)h(t)\xi(t)}{v(t, m_3^\varepsilon)} - \frac{m(t)h(t)\eta(t)M_3^\varepsilon}{v(t, M_3^\varepsilon)} \right\} > 0,$$

$$\inf_{t \geq t_0} \left\{ \frac{f(t)\gamma(t)m_1^\varepsilon}{u(t, m_1^\varepsilon, M_2^\varepsilon)} - \frac{\alpha(t)c(t)}{u(t, m_1^\varepsilon, m_2^\varepsilon)} - \frac{h(t)\xi(t)n(t)}{v(t, m_3^\varepsilon)} - \frac{\beta(t)c(t)M_1^\varepsilon}{u(t, M_1^\varepsilon, m_2^\varepsilon)} - \frac{h(t)n(t)\eta(t)M_3^\varepsilon}{v(t, M_3^\varepsilon)} \right\} > 0,$$

$$(9) \quad \inf_{t \geq t_0} \left\{ \frac{m(t)h(t)\eta(t)m_1^\varepsilon + n(t)h(t)\eta(t)m_2^\varepsilon}{v(t, M_3^\varepsilon)} - m(t) - n(t) \right\} > 0,$$

where

$$u(t, x, y) := [\alpha(t) + \beta(t)x^* + \gamma(t)y^*(t)][\alpha(t) + \beta(t)x(t) + \gamma(t)y(t)],$$

$$v(t, z) := [\xi(t) + \eta(t)z^*][\xi(t) + \eta(t)z]$$

then $(x^*(t), y^*(t), z^*(t))$ is globally asymptotically stable.

Proof. Let $(x(t), y(t), z(t))$ be any solution of (1) with positive initial value. Since Γ_ε is an ultimately bounded region of (1), there exists $T_1 > 0$ such that $(x(t), y(t), z(t)) \in \Gamma_\varepsilon$ and

$$(x^*(t), y^*(t), z^*(t)) \in \Gamma_\varepsilon \text{ for all } t \geq t_0 + T_1.$$

Considering a Liapunov function defined by

$$V(t) = |\ln(x(t)) - \ln(x^*(t))| + |\ln(y(t)) - \ln(y^*(t))| + |\ln(z(t)) - \ln(z^*(t))|, t \geq t_0$$

a direct calculation of the right derivative $D^+V(t)$ of $V(t)$ along the solution of (1) produces

$$\begin{aligned}
 (10) \quad D^+V(t) &= \operatorname{sgn}(x - x^*) \left(\frac{x'}{x} - \frac{x^{*'}}{x^*} \right) + \operatorname{sgn}(y - y^*) \left(\frac{y'}{y} - \frac{y^{*'}}{y^*} \right) \\
 &\quad + \operatorname{sgn}(z - z^*) \left(\frac{z'}{z} - \frac{z^{*'}}{z^*} \right) \\
 &= \operatorname{sgn}(x - x^*) \left[a - bx - \frac{cy}{\alpha + \beta x + \gamma y} - mz - a + bx^* + \frac{cy^*}{\alpha + \beta x^* + \gamma y^*} + mz^* \right] \\
 &\quad + \operatorname{sgn}(y - y^*) \left[-d + \frac{fx}{\alpha + \beta x + \gamma y} - nz + d - \frac{fx^*}{\alpha + \beta x^* + \gamma y^*} + nz^* \right] \\
 &\quad + \operatorname{sgn}(z - z^*) \left[\frac{h(mx + ny)}{\xi + \eta z} - \frac{h(mx^* + ny^*)}{\xi + \eta z^*} \right] \\
 &= \operatorname{sgn}(x - x^*) \left[-b(x - x^*) - m(z - z^*) - c \left(\frac{y}{\alpha + \beta x + \gamma y} - \frac{y^*}{\alpha + \beta x^* + \gamma y^*} \right) \right] \\
 &\quad - n \operatorname{sgn}(y - y^*)(z - z^*) + f \operatorname{sgn}(y - y^*) \frac{\alpha(x - x^*) + \gamma(xy^* - x^*y)}{u(t, x, y)} \\
 &\quad + h \operatorname{sgn}(z - z^*) \frac{(mx + ny)(\xi + \eta z^*) - (mx^* + ny^*)(\xi + \eta z)}{v(t, z)} \\
 &\leq -b|x - x^*| + m|z - z^*| + \frac{\alpha c|y - y^*|}{u(t, x, y)} + \operatorname{sgn}(x - x^*) \frac{\beta c(xy^* - x^*y)}{u(t, x, y)} \\
 &\quad + n|z - z^*| + \frac{\alpha f|x - x^*|}{u(t, x, y)} + \operatorname{sgn}(y - y^*) \frac{f\gamma(xy^* - x^*y)}{u(t, x, y)} \\
 &\quad + h \operatorname{sgn}(z - z^*) \frac{(mx + ny)(\xi + \eta z^*) - (mx^* + ny^*)(\xi + \eta z)}{v(t, z)}.
 \end{aligned}$$

We have

$$\begin{aligned}
 (mx + ny)(\xi + \eta z^*) - (mx^* + ny^*)(\xi + \eta z) &= \\
 &= m\xi(x - x^*) + n\xi(y - y^*) + m\eta(xz^* - x^*z) + n\eta(yz^* - y^*z)
 \end{aligned}$$

and

$$\begin{aligned} xy^* - x^*y &= x(y^* - y) + y(x - x^*), \\ xz^* - x^*z &= x(z^* - z) + z(x - x^*), \\ yz^* - y^*z &= y(z^* - z) + z(y - y^*). \end{aligned}$$

Thus,

$$\begin{aligned} (11) \quad D^+V(t) &\leq \left[-b + \frac{hm\xi}{v(t, z)} + \frac{\alpha f}{u(t, x, y)} + \frac{\beta cy + f\gamma y}{u(t, x, y)} + \frac{hm\eta z}{v(t, z)} \right] |x - x^*| + \\ &\quad + \left[\frac{\alpha c}{u(t, x, y)} + \frac{\beta cx - f\gamma x}{u(t, x, y)} + \frac{h\xi n + hn\eta z}{v(t, z)} \right] |y - y^*| + \\ &\quad + \left[m + n - \frac{hm\eta x + hn\eta y}{v(t, z)} \right] |z - z^*|. \end{aligned}$$

Because $(x(t), y(t), z(t)) \in \Gamma_\varepsilon$, for all $t \geq t_0 + T_1$, we get that

$$\begin{aligned} (12) \quad D^+V(t) &\leq - \left[b(t) - \frac{\alpha(t)f(t)}{u(t, m_1^\varepsilon, m_2^\varepsilon)} - \frac{\beta(t)c(t) + f(t)\gamma(t)}{u(t, m_1^\varepsilon, M_2^\varepsilon)} M_2^\varepsilon - \right. \\ &\quad \left. - \frac{m(t)h(t)\xi(t)}{v(t, m_3^\varepsilon)} - \frac{m(t)h(t)\eta(t)M_3^\varepsilon}{v(t, M_3^\varepsilon)} \right] |x - x^*| - \\ &\quad - \left[\frac{f(t)\gamma(t)m_1^\varepsilon}{u(t, m_1^\varepsilon, M_2^\varepsilon)} - \frac{\alpha(t)c(t)}{u(t, m_1^\varepsilon, m_2^\varepsilon)} - \frac{h(t)\xi(t)n(t)}{v(t, m_3^\varepsilon)} - \right. \\ &\quad \left. - \frac{\beta(t)c(t)M_1^\varepsilon}{u(t, M_1^\varepsilon, m_2^\varepsilon)} - \frac{h(t)n(t)\eta(t)M_3^\varepsilon}{v(t, M_3^\varepsilon)} \right] |y - y^*| - \\ &\quad - \left[\frac{m(t)h(t)\eta(t)m_1^\varepsilon + h(t)n(t)\eta(t)m_2^\varepsilon}{v(t, M_3^\varepsilon)} - n(t) - m(t) \right] |z - z^*|, \end{aligned}$$

for all $t \geq t_0 + T_1$. From (9) follows that there exists a positive constant $\mu > 0$ such that

$$(13) \quad D^+V(t) \leq -\mu[|x(t) - x^*(t)| + |y(t) - y^*(t)| + |z(t) - z^*(t)|],$$

for all $t \geq t_0 + T_1$.

Integrating on both sides of (13) from $t_0 + T_1$ to t produces

$$V(t) + \mu \int_{t_0+T_1}^t [|x(s) - x^*(s)| + |y(s) - y^*(s)| + |z(s) - z^*(s)|] ds \leq V(t_0 + T_1) < +\infty,$$

for all $t \geq t_0 + T_1$.

Then

$$\int_{t_0+T_1}^t [|x(s) - x^*(s)| + |y(s) - y^*(s)| + |z(s) - z^*(s)|] ds \leq \mu^{-1} V(t_0 + T_1) < +\infty,$$

for all $t \geq t_0 + T_1$,

Hence, $|x - x^*| + |y - y^*| + |z - z^*| \in L^1([t_0 + T_1, +\infty))$.

The boundedness of x^* , y^* , z^* and the ultimate boundedness of $x(t)$, $y(t)$, $z(t)$ imply that $x(t)$, $y(t)$, $z(t)$, $x^*(t)$, $y^*(t)$ and $z^*(t)$ all have bounded derivatives for $t \geq t_0 + T_1$ (from the equations satisfied by them). As a consequence

$$|x(s) - x^*(s)| + |y(s) - y^*(s)| + |z(s) - z^*(s)|$$

is uniformly continuous on $[t_0 + T_1, +\infty)$.

By Lemma 2 we have

$$\lim_{t \rightarrow \infty} (|x(t) - x^*(t)| + |y(t) - y^*(t)| + |z(t) - z^*(t)|) = 0$$

which completes the proof. $\square$

ACKNOWLEDGMENT

The author would like to thank professor Nguyen Huu Du for his interest, encouragement, fruitful discussions and helpful comments.

REFERENCES

- [1] S. Ahmad. On the nonautonomous Volterra-Lotka competition equations. *Proc. Amer. Math. Soc.*, 117(1):199–204, 1993.
- [2] I. Barbălat. Systèmes d'équations différentielles d'oscillations non linéaires. *Rev. Math. Pures Appl.*, 4:267–270, 1959.
- [3] J. R. Beddington. Mutual interference between parasites or predators and its effect on searching efficiency. *J. Animal Ecol.*, 44(1):331–340, 1975.
- [4] R. S. Cantrell and C. Cosner. On the dynamics of predator-prey models with the Beddington-DeAngelis functional response. *J. Math. Anal. Appl.*, 257(1):206–222, 2001.
- [5] N. H. Du, R. Kon, K. Sato, and Y. Takeuchi. Dynamical behavior of Lotka-Volterra competition systems: non-autonomous bistable case and the effect of telegraph noise. *J. Comput. Appl. Math.*, 170(2):399–422, 2004.
- [6] N. H. Du, R. Kon, K. Sato, and Y. Takeuchi. The evolution of periodic population systems under random environments. *Tohoku Math. J. (2)*, 57(4):447–468, 2005.
- [7] M. Fan and Y. Kuang. Dynamics of a nonautonomous predator-prey system with the Beddington-DeAngelis functional response. *J. Math. Anal. Appl.*, 295(1):15–39, 2004.
- [8] T.-W. Hwang. Global analysis of the predator-prey system with Beddington-DeAngelis functional response. *J. Math. Anal. Appl.*, 281(1):395–401, 2003.
- [9] T.-W. Hwang. Uniqueness of limit cycles of the predator-prey system with Beddington-DeAngelis functional response. *J. Math. Anal. Appl.*, 290(1):113–122, 2004.
- [10] Y. Pinghua and X. Rui. Global attractivity of the periodic Lotka-Volterra system. *J. Math. Anal. Appl.*, 233(1):221–232, 1999.
- [11] Y. Takeuchi. *Global dynamical properties of Lotka-Volterra systems*. World Scientific Publishing Co. Inc., River Edge, NJ, 1996.
- [12] Y. Takeuchi, N. H. Du, N. T. Hieu, and K. Sato. Evolution of predator-prey systems described by a Lotka-Volterra equation under random environment. *J. Math. Anal. Appl.*, 323(2):938–957, 2006.

Received September 19, 2007.

FACULTY OF MATHEMATICS, MECHANICS AND INFORMATICS,
COLLEGE OF SCIENCE,
VIETNAM NATIONAL UNIVERSITY,
HANOI,
VIETNAM.
E-mail address: `tontv@vnu.edu.vn`